LETTERS TO THE EDITOR

# VIBRATIONS OF A BEAM OF NON-UNIFORM CROSS-SECTION TRAVERSED BY A TIME VARYING CONCENTRATED FORCE 

R. H. Gutierrez and P. A. A. Laura

Institute of Applied Mechanics (CONICET) and Department of Engineering, Universidad Nacional del Sur, 8000-Bahía Blanca, Argentina
(Received 18 October 1996, and in final form 20 May 1997)

## 1. INTRODUCTION

The analysis of the dynamic behavior of structural elements traversed by moving forces or masses is certainly a classical problem which has attracted the attention of many researchers. The reader is referred to comprehensive listing of references available in well known textbooks and papers [1-8]. In general the investigations have been motivated by the necessity of evaluating the dynamic behavior of a bridge travelled by a car or of rails travelled by a train.

The present paper, considerable more modest in its scope, deals with the approximate determination of the transverse response of the structural system depicted in Figure 1 as a load

$$
\begin{equation*}
P(t)=P_{0} \mathrm{e}^{-\alpha t} \tag{1}
\end{equation*}
$$

which travels at constant speed, $v$, along the beam. The beam, of constant width $b$, is characterized by a parabolically varying thickness given by

$$
\begin{equation*}
h(\bar{x})=h_{m} f(\bar{x})=h_{m}\left[4(\gamma-1)\left(\bar{x}^{2} / L^{2}-\bar{x} / L\right)+\gamma\right], \tag{2}
\end{equation*}
$$

where

$$
\gamma=h(0) / h_{m} .
$$

Consequently, the cross-sectional area of the beam is

$$
\begin{equation*}
A(\bar{x})=b h_{m} f(\bar{x})=A_{m} f(\bar{x}), \quad A_{m}=b h_{m}, \tag{3a}
\end{equation*}
$$

and the moment of inertia is given by

$$
\begin{equation*}
I(\bar{x})=b h_{m}^{3} f^{3}(\bar{x}) / 12=I_{m} f^{3}(\bar{x}), \quad I_{m}=b h_{m}^{3} / 12 \tag{3b}
\end{equation*}
$$

Three arrangements of boundary conditions will be considered: simply supported at both ends, clamped, simply supported and clamped at both ends.

Neglecting inertia effects of the load itself the governing differential system is

$$
\begin{gather*}
E \frac{\partial^{2}}{\partial \bar{x}^{2}}\left(I(\bar{x}) w_{\bar{x}^{2}}\right)+\rho A(\bar{x}) w_{t^{2}}=\delta(\bar{x}-v t) P_{0} \mathrm{e}^{-\alpha t}, \quad \alpha>0,  \tag{4}\\
w(\bar{x}, 0)=w_{t}(\bar{x}, 0)=0 \tag{5}
\end{gather*}
$$

where shear and rotatory inertia effects have been disregarded since a first order approximation is being sought.

The following two sections deal (1) with an exact solution of equations (4) and (5) in the case where the beam possesses a uniform thickness and (2) an approximate solution of the problem when $h(\bar{x})$ is given by equation (2).

## 2. EXACT ANALYTICAL SOLUTION

Making $\gamma=1$ in equation (2) and substituting equations (2) and (3) in equation (4) results in

$$
\begin{equation*}
E I_{m} w_{\bar{x}^{4}}+\rho A_{m} w_{t^{2}}=\delta(\bar{x}-v t) P_{0} \mathrm{e}^{-\alpha t} \tag{6}
\end{equation*}
$$

Let $T$ be the time interval needed by the load $P(t)$ to traverse the beam. Accordingly,

$$
\begin{equation*}
\delta(\bar{x}-v t)=\delta(L x-L t / T)=\delta(L(x-t / T))=\delta(x-t / T) / L \tag{7}
\end{equation*}
$$

Substituting equation (7) in equation (6) and introducing the dimensionless variable $x=\bar{x} / L$ one obtains

$$
\begin{equation*}
w_{x^{4}}+\beta_{1} w_{t^{2}}=\beta_{2} P_{0} \delta(x-t / T) \mathrm{e}^{-\alpha t} \tag{8}
\end{equation*}
$$

where

$$
\beta_{1}=\rho A_{m} L^{4} /\left(E I_{m}\right), \quad \beta_{2}=L^{3} /\left(E I_{m}\right)
$$

It is convenient to introduce the dimensionless displacement variable $u(x, t)$, where

$$
\begin{equation*}
u(x, t)=w(x, t) / w_{e} \tag{9}
\end{equation*}
$$

and where $w_{e}$ is the maximum displacement introduced by a static load $P_{0}$ acting at $\bar{x}=L / 2$.
Accordingly

$$
\begin{equation*}
w_{e}=P_{0} L^{3} /\left(\zeta E I_{m}\right) . \tag{10}
\end{equation*}
$$

Obviously the maximum static displacement occurs at $\bar{x}=L / 2$ for the first and third type of boundary conditions and at $\bar{x}=L(1-1 / \sqrt{5})$ when the beam is clamped-simply supported.
The values of $\zeta$ are $\zeta=48$ (simply-supported case), $\zeta=48 \sqrt{5}$ (clamped-simply supported) and $\zeta=192$ (clamped at both ends).

Substituting equation (9) in equation (8) results in

$$
\begin{equation*}
u_{x^{4}}+\beta_{1} u_{t^{2}}=\zeta \delta(x-t / T) \mathrm{e}^{-\alpha t} \tag{11}
\end{equation*}
$$



Figure 1. Vibrating system under study.

Making

$$
\begin{equation*}
u(x, t)=\sum_{n=1}^{\infty} \varphi_{n}(x) \psi_{n}(t) \tag{12}
\end{equation*}
$$

where the $\varphi_{n}(x)$ 's are the normal modes of the structure, and substituting equation (12) in equation (11) results in

$$
\begin{equation*}
\psi_{n}(t)+\omega_{n}^{2} \psi_{n}(t)=k_{n} \varphi_{n}(t / T) \mathrm{e}^{-\alpha t} \tag{13}
\end{equation*}
$$

once usual normal mode operating procedures are performed and where the $\omega_{n}$ 's are the natural circular frequencies of the system and

$$
\begin{equation*}
k_{n}=\zeta /\left(\beta_{1} \int_{0}^{1} \varphi_{n}^{2}(x) \mathrm{d} x\right) \tag{14}
\end{equation*}
$$

Making

$$
\mu_{n}^{2}=\sqrt{\beta_{1}} \omega_{n}
$$

the normalized normal modes are, in the case of simply supported beams,

$$
\begin{equation*}
\varphi_{n}(x)=\sin \mu_{n} x, \quad \mu_{n}=n \pi \tag{15}
\end{equation*}
$$

In the case of clamped-simply supported and clamped-clamped beams,

$$
\begin{equation*}
\varphi_{n}(x)=\cosh \mu_{n} x-\cos \mu_{n} x-c_{n}\left(\sinh \mu_{n} x-\sin \mu_{n} x\right) \tag{16}
\end{equation*}
$$

with

$$
C_{n}=\left(\cosh \mu_{n}-\cos \mu_{n}\right) /\left(\sinh \mu_{n}-\sin \mu_{n}\right)
$$

Then, the particular solution of equation (13) is

$$
\begin{equation*}
\psi_{n P}(t)=\mathrm{e}^{-\alpha_{t}}\left(k_{1} \cosh \frac{\mu_{n} t}{T}+k_{2} \cos \frac{\mu_{n} t}{T}+k_{3} \sinh \frac{\mu_{n} t}{T}+k_{4} \sin \frac{\mu_{n} t}{T}\right) \tag{17}
\end{equation*}
$$

and the general solution of equation (13) results in

$$
\begin{equation*}
\psi_{n}(t)=C_{1 n} \cos \omega_{n} t+C_{2 n} \sin \omega_{n} t+\psi_{n P}(t) \tag{18}
\end{equation*}
$$

where $C_{1 n}$ and $C_{2 n}$ are determined using the initial conditions $\psi_{n}(0)=\dot{\psi}_{n}(0)=0$. If the beam is simply supported one has $k_{1}=k_{3}=0$; for the other types of boundary conditions the four constants are different from zero.

Finally the solutions to the posed problem is

$$
\begin{equation*}
u(x, t)=\sum_{n=1}^{\infty}\left[C_{1 n} \cos \omega_{n} t+C_{2 n} \sin \omega_{n} t+\psi_{n P}(t)\right] \varphi_{n}(x) \tag{19}
\end{equation*}
$$

## 3. APPROXIMATE SOLUTION: CASE OF A BEAM OF NON-UNIFORM CROSS-SECTION

Substituting equations (3) and (9) in equation (4) and introducing the dimensionless variables $x=\bar{x} / L$ and $\tau=t / T$ one obtains

$$
\begin{equation*}
f^{3} u_{x^{4}}+6 f^{2} f^{\prime} u_{x^{3}}+3\left(f f^{\prime 2}+f^{2} f^{\prime \prime}\right) u_{x^{2}}+\frac{\beta_{1}}{T^{2}} f u_{\tau^{2}}=\zeta \delta(x-\tau) \mathrm{e}^{-\alpha T \tau} \tag{20}
\end{equation*}
$$

subject to the governing boundary and initial conditions.

Making use of the Galerkin-Kantorovich method one expresses

$$
\begin{equation*}
u \simeq u_{\alpha}=\varphi(x) \psi(\tau) \tag{21}
\end{equation*}
$$

where $\varphi(x)$ will be constructed in such a way as to satisfy the beam boundary conditions. Substituting equation (21) in equation (20) one obtains, after application of Galerkin's orthogonalization procedure,

$$
\begin{equation*}
J_{1} \ddot{\psi}(\tau)+J_{2} \psi(\tau)=\zeta \mathrm{e}^{-\alpha T \tau} \varphi(\tau) \tag{22}
\end{equation*}
$$

where

$$
J_{1}=\frac{\beta_{1}}{T^{2}} \int_{0}^{1} f \varphi^{2} \mathrm{~d} x, \quad J_{2}=\int_{0}^{1}\left[f^{3} \varphi^{I V}+6 f^{2} f^{\prime} \varphi^{\prime \prime \prime}+3\left(f f^{\prime 2}+f^{2} f^{\prime \prime}\right) \varphi^{\prime \prime}\right] \varphi \mathrm{d} x
$$

It is convenient to express $\varphi(x)$ in the form

$$
\begin{equation*}
\varphi(x)=x^{4}+\alpha_{3} x^{3}+\alpha_{2} x^{2}+\alpha_{1} x \tag{23}
\end{equation*}
$$

where the $\alpha_{i}$ 's are obtained by substituting equation (23) in the boundary conditions [9-11]. The particular solution of equation (22) is

$$
\begin{equation*}
\psi_{P}(\tau)=\mathrm{e}^{-\alpha T \tau}\left(k_{4} \tau^{4}+k_{3} \tau^{3}+k_{2} \tau^{2}+k_{1} \tau+k_{0}\right) \tag{24}
\end{equation*}
$$

and its general solution becomes

$$
\begin{equation*}
\psi(\tau)=C_{1} \cos v \tau+C_{2} \sin v \tau+\psi_{P}(\tau), \quad v=\sqrt{J_{2} / J_{1}} \tag{25}
\end{equation*}
$$

where $C_{1}$ and $C_{2}$ are determined applying the boundary conditions.

## 4. RESULTS AND CONCLUSIONS

Numerical experiments have been performed making $\beta_{1}=0.02$ and 0.35 . With regards to the acting force $P(t)=P_{0} \mathrm{e}^{-\alpha t}$ three situations have been considered: constant value $(\alpha=0) ; P(T) / P_{0}=0 \cdot 70, \alpha=0 \cdot 118892(T=3 \mathrm{~s}) ; P(T) / P_{0}=0 \cdot 30, \alpha=0.401324(T=3 \mathrm{~s})$. The values of $u(x, t)$ have been plotted as a function of $t$ at the beam center for the simply supported and clamped cases at both ends, and at $x=1-1 / \sqrt{5}$ for the clamped-simply supported situation.

Figures $2-5$ deal with beams of uniform thickness. Figures 2 and 3 depict values of $u(x, t)$ for the simply supported case for $\beta_{1}=0.02$ and $0 \cdot 35$, respectively, while Figures 4 and 5 show results for the clamped-simply supported and clamped-clamped situations, respectively, for $\beta_{1}=0.02$. No significant variations were observed for the cases treated in Figures 4 and 5 when $\beta_{1}$ was taken equal to $0 \cdot 35$.

Good agreement is observed between the exact values and those obtained by means of the variational approach (six terms were employed when using the exact, normal mode approach).

Figures 6-9 deal with beams of non-uniform thickness $(\gamma=1 \cdot 30)$. All calculations have been performed for $T=3 \mathrm{~s} ; \beta_{1}=0.02$ and 0.35 . It is again observed, when performing the numerical determinations, that in the case of clamped-simply supported and clamped-clamped ends practically the same results are obtained for $\beta_{1}=0.02$ and $\beta_{1}=0 \cdot 35$.

The proposed approach is quite simple and straightforward. The cases of ends elastically restrained against translation and rotation do not offer any conceptual and/or operational difficulties.


Figure 2. Plot of $u(0 \cdot 5, t)$ in the case of a simply supported beam $\left(\beta_{1}=0 \cdot 02, \gamma=1\right)$ : —, exact solution; $\bigcirc$, variational solution; $p=P(T) / P_{0}$.


Figure 3. Plot of $u(0 \cdot 5, t)$ in the case of a simply supported beam $\left(\beta_{1}=0 \cdot 35, \gamma=1\right)$ : - , exact solution; $\bigcirc$, variational solution.


Figure 4. Plot of $u(1-1 \sqrt{5}, t)$ in the case of a clamped-simply supported beam $\left(\beta_{1}=0 \cdot 02, \gamma=1\right):-$ exact solution; $\bigcirc$, variational approach.


Figure 5. Plot of $u(0 \cdot 5, t)$ in the case of a clamped-clamped beam $\left(\beta_{1}=0 \cdot 02, \gamma=1\right)$ :- , exact solution; $\bigcirc$, variational solution.
t


Figure 6. Plot of $u(0 \cdot 5, t)$ in the case of a simply supported beam of non-uniform thickness $\left(\beta_{1}=0 \cdot 021\right.$, $\gamma=1 \cdot 30$ ).


Figure 7. Plot of $u(0 \cdot 5, t)$ in the case of a simply supported beam of non-uniform thickness $\left(\beta_{1}=0 \cdot 35\right.$, $\gamma=1 \cdot 30$ ).


Figure 8. Plot of $u(1-1 / \sqrt{5}, t)$ in the case of a clamped-simply supported beam of non-uniform thickness ( $\beta_{1}=0.02, \gamma=1 \cdot 30$ ).


Figure 9. Plot of $u(0.5, t)$ in the case of a clamped-clamped beam of non-uniform thickness ( $\beta_{1}=0.02$, $\gamma=1 \cdot 30$ ).

## ACKNOWLEDGMENTS

The present study has been sponsored by CONICET Research and Development Program (PIA 1996-1997) and by Secretaría General de Ciencia y Tecnología of the Universidad Nacional del Sur.

## REFERENCES

1. S. Timoshenko 1955 Vibration Problems in Engineering. Third edition. New York, N.Y.: D. Van Nostrand.
2. E. Volterra and E. C. Zachmanoglou 1965 Dynamics of Vibrations. Columbus, Ohio: C. E. Merril Books.
3. L. Fríba 1972 Vibrations of Solids and Structures under Moving Loads. Gröningen: Noordhoff International.
4. M. Géradin and D. Rixen 1994 Mechanical Vibrations. New York, Paris: Wiley-Masson.
5. A. Dimarogonas 1996 Vibration for Engineers. Second edition. Englewood Cliffs, New Jersey: Prentice Hall.
6. M. M. Stanisic and J. C. Hardin 1967 Journal of the Franklin Institute 287, 115-123. On the response of beams to an arbitrary number of concentrated moving masses.
7. M. M. Stanisic, J. A. Euler and S. T. Montgomery 1974 Ingenieur-Archive 43, 295-305. On a theory concerning the dynamical behavior of structures carrying moving masses.
8. F. Khalily, M. F. Golnaraghi and G. R. Heppler 1994 Nonlinear Dynamics 5, 493-513. On the dynamic behavior of a flexible beam carrying a moving mass.
9. P. A. A. Laura and B. F. Saffel 1967 The Journal of the Acoustical Society of America 41, 836-838. Study of small amplitude vibrations of clamped rectangular plates using polynomial approximations.
10. P. A. A. Laura and E. Romanelli 1974 Journal of Sound and Vibration 37, 367-377. Vibrations of rectangular plates elastically restrained against rotation and subjected to a bi-axial state of stress.
11. R. H. Gutierrez and P. A. A. Laura 1996 Journal of Sound and Vibration 195, 353-358. Transverse vibrations of beams traversed by point masses: a general approximate solution.
